

# A Simple P-matrix Linear Complementarity Problem for Discounted Games

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# Motivation

- ▶ **Discounted games**

- ▶ polytime reductions from **parity** and **mean-payoff** games
- ▶ simple optimality equations give “transparent” reduction

- ▶ **P-matrix Linear Complementarity Problem**

- ▶ well studied problem in mathematical programming
- ▶ many algorithms known

# Outline

- ▶ **P-matrix Linear Complementarity Problem**

- ▶ **Unique sink orientations (USO) of cubes**

- combinatorial framework for strategy improvement algorithms

- ▶ **Discounted games**

- ▶ Optimality equations characterize unique values

- ▶ **Reduction** from **discounted games** to **PLCP**

- ▶ Connections between algorithms

- ▶ **Further research**

# Linear Complementarity Problem (LCP)

Given:  $\mathbf{q} \in \mathbb{R}^n$ ,  $\mathbf{M} \in \mathbb{R}^{n \times n}$  Find:  $\mathbf{z}, \mathbf{w} \in \mathbb{R}^n$  so that

$$\mathbf{z} \geq 0 \quad \perp \quad \mathbf{w} = \mathbf{q} + \mathbf{M}\mathbf{z} \geq 0$$

$\perp$  means orthogonal:

$$\mathbf{z}^T \mathbf{w} = 0$$

$$\Leftrightarrow \mathbf{z}_i \mathbf{w}_i = 0 \quad \text{all } i = 1, \dots, n$$

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If  $\mathbf{q} \geq 0$ , the LCP has trivial solution  $\mathbf{w} = \mathbf{q}$ ,  $\mathbf{z} = 0$ .

# LP in inequality form

$$\begin{array}{ll}\text{primal : } & \max \quad c^T \mathbf{x} \\ & \text{subject to} \quad \mathbf{A} \mathbf{x} \leq \mathbf{b} \\ & \quad \mathbf{x} \geq \mathbf{0}\end{array}$$

$$\begin{array}{ll}\text{dual : } & \min \quad \mathbf{y}^T \mathbf{b} \\ & \text{subject to} \quad \mathbf{y}^T \mathbf{A} \geq \mathbf{c}^T \\ & \quad \mathbf{y} \geq \mathbf{0}\end{array}$$

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**Weak duality:**  $\mathbf{x}$ ,  $\mathbf{y}$  feasible (fulfilling constraints)

$$\Rightarrow \mathbf{c}^T \mathbf{x} \leq \mathbf{y}^T \mathbf{A} \mathbf{x} \leq \mathbf{y}^T \mathbf{b}$$

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**Strong duality:** primal and dual feasible

$$\Rightarrow \exists \text{ feasible } \mathbf{x}, \mathbf{y} : \mathbf{c}^T \mathbf{x} = \mathbf{y}^T \mathbf{b} \quad (\mathbf{x}, \mathbf{y} \text{ optimal})$$



# LCP generalizes LP

LCP encodes **complementary slackness** of strong duality:

$$\begin{aligned} & c^T \mathbf{x} = \mathbf{y}^T \mathbf{A} \mathbf{x} = \mathbf{y}^T \mathbf{b} \\ \Leftrightarrow & (\mathbf{y}^T \mathbf{A} - c^T) \mathbf{x} = 0, \quad \mathbf{y}^T (\mathbf{b} - \mathbf{A} \mathbf{x}) = 0. \\ & \geq 0 \quad \geq 0 \quad \geq 0 \quad \geq 0 \end{aligned}$$

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 & \quad \geq 0 \quad \geq 0 \quad \geq 0 \quad \geq 0
 \end{aligned}$$

LP  $\Leftrightarrow$  LCP

$$\underbrace{\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix}}_z \geq 0 \quad \perp \quad \underbrace{\begin{pmatrix} -c \\ b \end{pmatrix}}_q + \underbrace{\begin{pmatrix} 0 & \mathbf{A}^T \\ -\mathbf{A} & 0 \end{pmatrix}}_M \underbrace{\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix}}_z \geq 0$$

# LCPs and complementary cones

Given:  $q \in \mathbb{R}^n$ ,  $M \in \mathbb{R}^{n \times n}$  Find:  $z \in \mathbb{R}^n$  so that

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$\Leftrightarrow q$  belongs to a **complementary cone**:

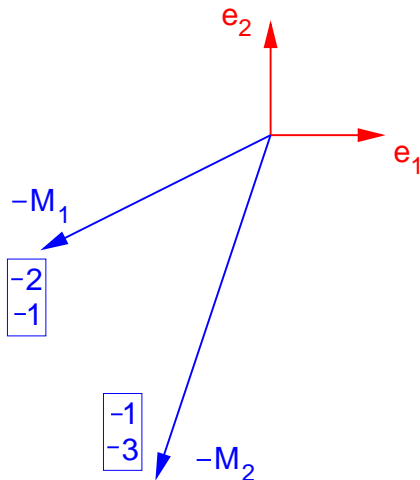
$$\boxed{q \in C(\alpha) = \text{cone} \{-M_i, e_j \mid i \in \alpha, j \notin \alpha\}}$$

for some  $\alpha \subseteq \{1, \dots, n\}$ ,  $M = [M_1 M_2 \cdots M_n]$

$$\alpha = \{i \mid z_i > 0\}$$

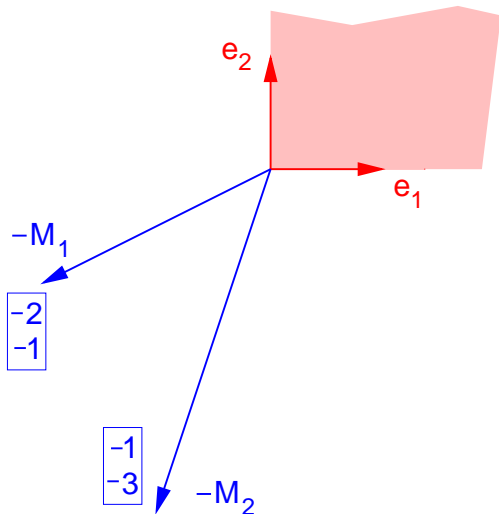
# LCPs and complementary cones

$$M = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix}$$



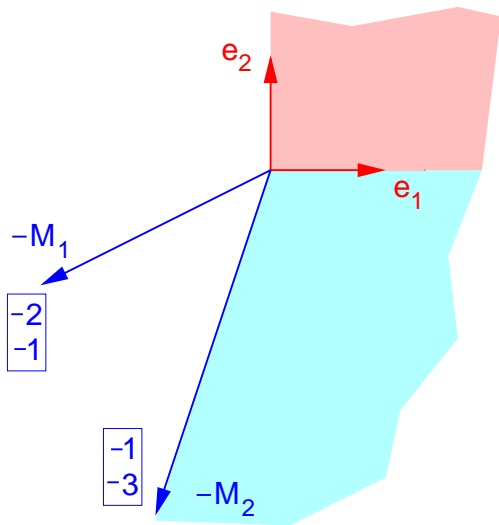
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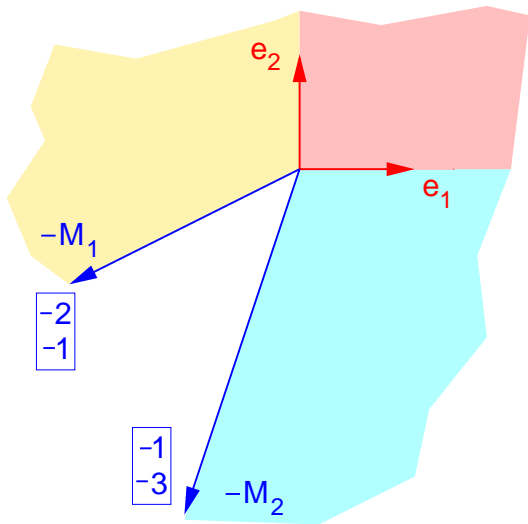
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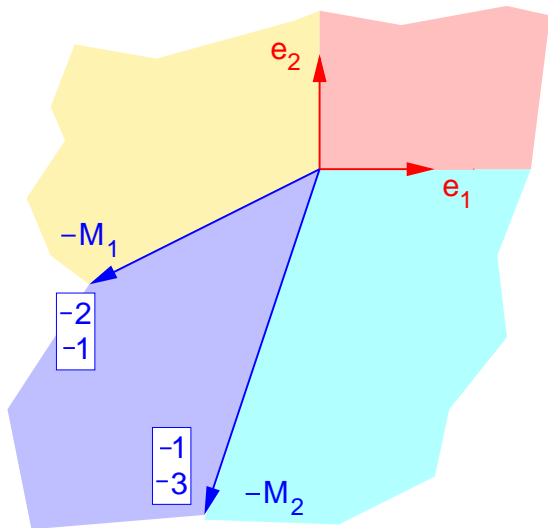
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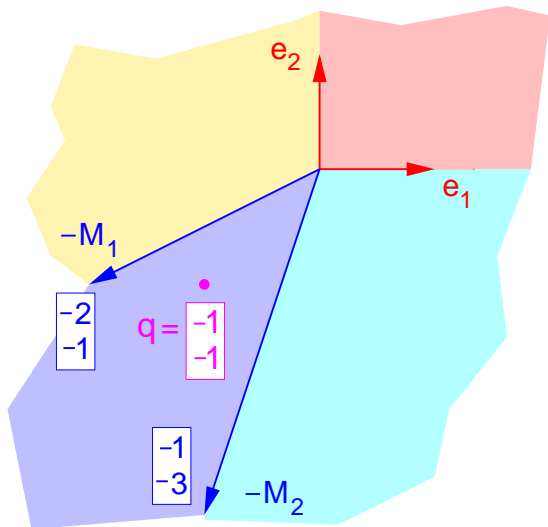
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# P-matrices

**Def:**  $M \in \mathbb{R}^{n \times n}$  is a **P-matrix** if **all** its **principal minors** are **positive**.

**Thm:**  $M$  is a **P-matrix**  $\Leftrightarrow$  LCP  $(M, q)$  has **unique solution**  $\forall q \in \mathbb{R}^n$ .

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## Example

$$M = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \quad M' = \begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix}$$

$M$  is a P-matrix, as

$$\det(M_{11}) = 2 > 0$$

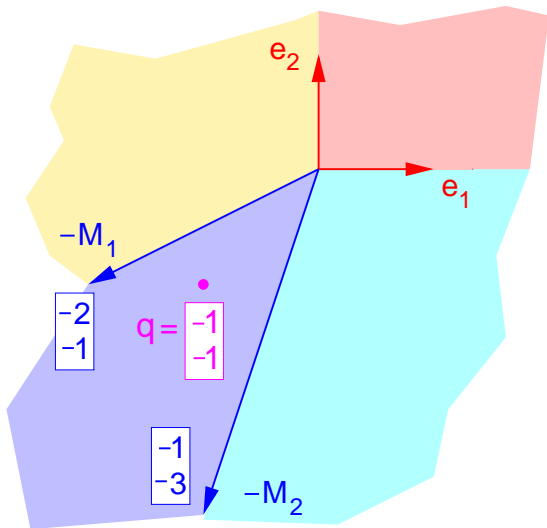
$$\det(M_{22}) = 3 > 0$$

$$\det(M) = 5 > 0$$

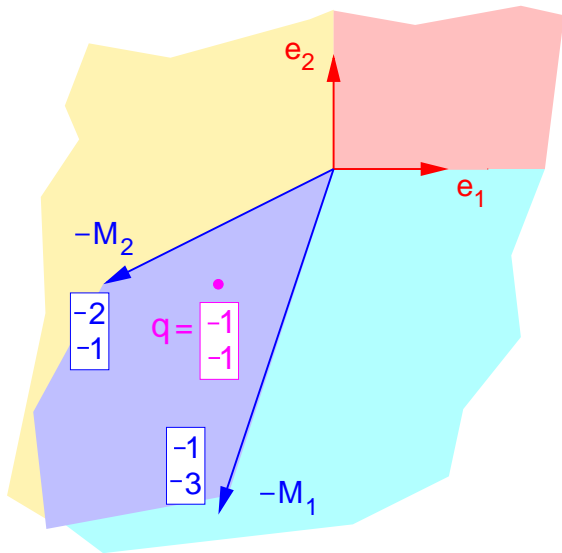
$M'$  is not a P-matrix, as  $\det(M') = -5 < 0$

# Complementary cones: P-matrix

$$M = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix}$$



# Multiple solutions



# Unique sink orientations of cubes

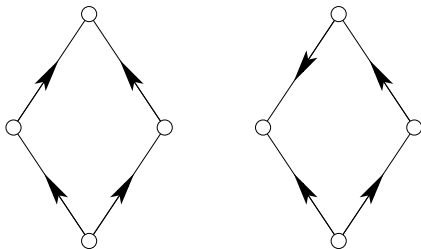
[Szabó and Welzl (2001)] [Stickney and Watson (1978)]

=

- ▶  $n$ -dimensional hypercube
- ▶ edges oriented such that **every face** has a **unique sink**

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The two USOs for  $n = 2$ :





# USO for P-matrix LCP

$$\text{LCP: } \mathbf{z} \geq \mathbf{0} \perp \mathbf{w} \geq \mathbf{0}, \quad \boxed{\mathbf{q} = \mathbf{I}\mathbf{w} - \mathbf{M}\mathbf{z}}$$

For every  $\alpha \subseteq \{1, \dots, n\}$ , define  $\mathbf{B}^\alpha \in \mathbb{R}^{n \times n}$  by

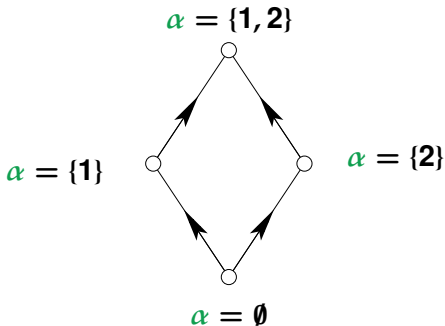
$$(\mathbf{B}^\alpha)_i = \begin{cases} -\mathbf{M}_i, & i \in \alpha \\ \mathbf{e}_i, & i \notin \alpha \end{cases}$$

Orient edges at vertex  $\alpha$  oriented according to

$$\text{sign} \left( (\mathbf{B}^\alpha)^{-1} \mathbf{q} \right)$$

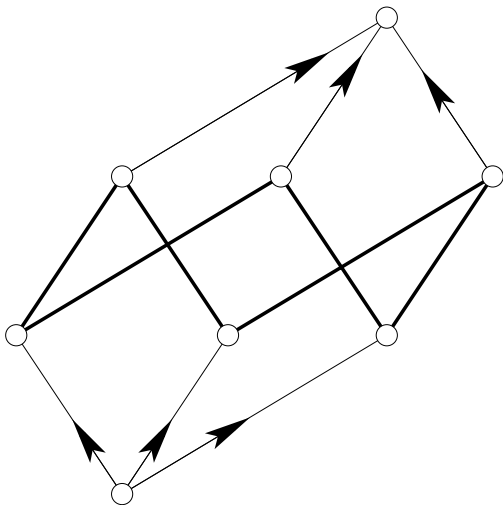
## PLCP USO example

$$-1/5 \begin{pmatrix} 3 & -1 \\ -1 & 2 \end{pmatrix} \mathbf{z}' + \mathbf{l}\mathbf{w}' = \mathbf{q}' = \begin{pmatrix} 2/5 \\ 1/5 \end{pmatrix} \geq 0$$



$$\mathbf{l}\mathbf{w} - \mathbf{M}\mathbf{z} = \mathbf{l}\mathbf{w} - \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \mathbf{z} = \mathbf{q} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

## Cyclic USO



Cyclic USOs can arise from P-matrix LCPs.

# Murty's Least Index Method

**Input:** LCP( $M, q$ ) with P-matrix  $M$ .

**Output:** solution  $(w^*, z^*)$

---

Start with  $\alpha := \emptyset, \bar{q} := q$ .

**while**  $\bar{q} \not\geq 0$  **do:**

- ▶ Let  $s = \min_{\{1, \dots, n\}} \{i \mid \bar{q}_i < 0\}$ ,
  - ▶ Set  $\alpha \leftarrow \alpha \oplus s$  and  $\bar{q} \leftarrow (B^\alpha)^{-1} q$ .
- 

**Why does it work?**

when  $\bar{q}_1, \dots, \bar{q}_{n-1} \geq 0$ , we determine  $w_n^* = 0$  or  $z_n^* = 0$ .

# Binary zero-sum discounted games

- ▶ Finite directed graph on states  $\mathbf{S} = \{1, \dots, n\}$
- ▶ Partition  $\mathbf{S} = \mathbf{S}_{\text{Max}} \cup \mathbf{S}_{\text{Min}}$

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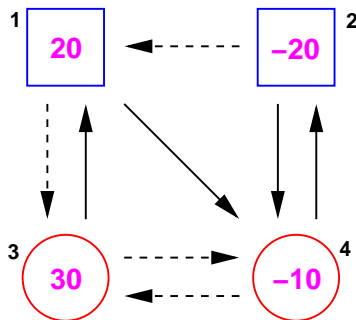
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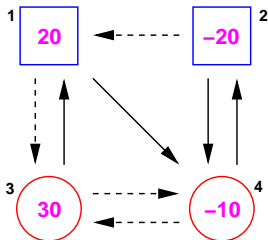


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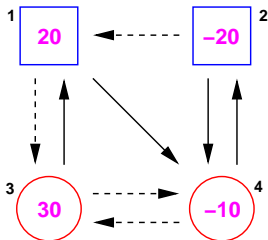


# Player objectives



- ▶ A play is an infinite path  $\pi = s_0, s_1, s_3, \dots$ 
  - ▶ initial state  $s_0$
  - ▶ owner of  $s_i$  chooses  $s_{i+1} \in \{ \lambda(s_i), \rho(s_i) \}$

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  - ▶ owner of  $\mathbf{s}_i$  chooses  $\mathbf{s}_{i+1} \in \{ \lambda(\mathbf{s}_i), \rho(\mathbf{s}_i) \}$
- ▶ **Max** maximizes and **Min** minimizes

$$\sum_{i=0}^{\infty} \delta^i r(\mathbf{s}_i)$$

# Optimality equations

- ▶ Every state has a **value**  $v(s)$  characterized by:

$$\forall s \in S_{\text{Max}} : \quad v(s) = \max_{t \in \{\lambda(s), \rho(s)\}} (r(s) + \delta v(t))$$

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  - ▶ **Banach fixed point theorem** for **contraction** mappings
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# Optimality equations

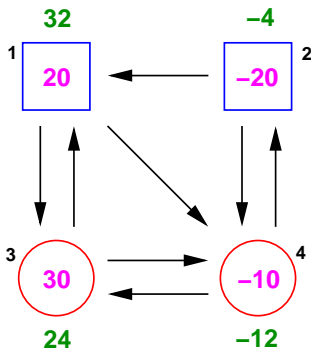
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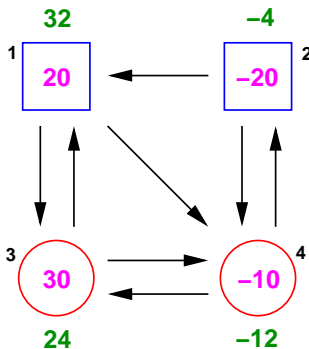
- ▶ Proofs:
  - ▶ **Banach fixed point theorem** for **contraction** mappings
  - ▶ **Strategy improvement** algorithm (constructive)
- ▶ Values give **pure** and **positional optimal strategies**:  
**Max** (**Min**) picks successor with **largest** (**smallest**) value.

## Unique values for $\delta = 1/2$



$$v(1) = 32 = r(1) + \delta \max(v(3), v(4)) = 20 + 1/2(24)$$

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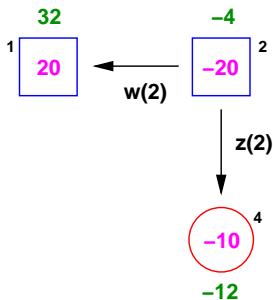


$v(1) = 32$	$= r(1) + \delta \max(v(3), v(4)) =$	$20 + 1/2(24)$
$v(2) = -4$	$= r(2) + \delta \max(v(1), v(4)) =$	$-20 + 1/2(32)$
$v(3) = 24$	$= r(3) + \delta \min(v(1), v(4)) =$	$30 + 1/2(-12)$
$v(4) = -12$	$= r(4) + \delta \min(v(2), v(3)) =$	$-10 + 1/2(-4)$



# Nonnegative slacks and complementarity

$$v(2) = r(2) + \delta \max(v(1), v(4))$$



$$v(2) = w(2) + r(2) + \delta v(1)$$

$$v(2) = z(2) + r(2) + \delta v(4)$$

$$w(2), z(2) \geq 0, \quad w(2) \cdot z(2) = 0$$

## Reduction to LCP

$$\forall \mathbf{s} \in S_{\text{Max}} : \quad \mathbf{v}(\mathbf{s}) = \max_{t \in \{\lambda(\mathbf{s}), \rho(\mathbf{s})\}} (r(\mathbf{s}) + \delta \mathbf{v}(t))$$

Replace **max/min** with **slacks** and **complementarity condition**

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$$\forall s \in S_{\text{Max}} : \quad v(s) = w(s) + r(s) + \delta v(\lambda(s))$$

$$v(s) = z(s) + r(s) + \delta v(\rho(s))$$

$$\forall s \in S : \quad w(s) \geq 0 \perp z(s) \geq 0$$

## Reduction to LCP

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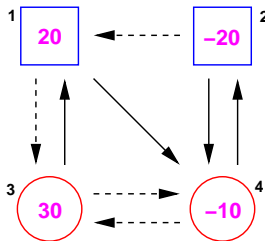
$$\mathbf{v}(s) = z(s) + r(s) + \delta \mathbf{v}(\rho(s))$$

$$\forall s \in S_{\text{Min}} : \quad \mathbf{v}(s) = -w(s) + r(s) + \delta \mathbf{v}(\lambda(s))$$

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$$\forall s \in S : \quad w(s) \geq 0 \quad \perp \quad z(s) \geq 0$$

# Example



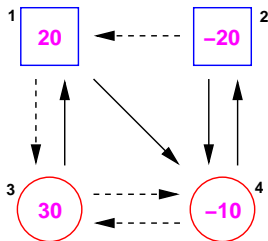
$\forall s \in S :$

$$w(v) \geq 0 \perp z(v) \geq 0$$

$$\begin{pmatrix} v(1) \\ v(2) \\ -v(3) \\ -v(4) \end{pmatrix} = \begin{pmatrix} w(1) \\ w(2) \\ w(3) \\ w(4) \end{pmatrix} + \begin{pmatrix} r(1) \\ r(2) \\ -r(3) \\ -r(4) \end{pmatrix} + \delta \begin{pmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} v(1) \\ v(2) \\ v(3) \\ v(4) \end{pmatrix}$$

$$\begin{pmatrix} v(1) \\ v(2) \\ -v(3) \\ -v(4) \end{pmatrix} = \begin{pmatrix} z(1) \\ z(2) \\ z(3) \\ z(4) \end{pmatrix} + \begin{pmatrix} r(1) \\ r(2) \\ -r(3) \\ -r(4) \end{pmatrix} + \delta \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} v(1) \\ v(2) \\ v(3) \\ v(4) \end{pmatrix}$$

# Example



$$w \geq 0 \perp z \geq 0$$

$$A := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$A v = w + A r + \delta A \overbrace{\begin{pmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}}^L v$$

$$A v = z + A r + \delta A \underbrace{\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}}_R v$$

## Eliminate $v$

$$A(I - \delta L)v = w + Ar$$

$$A(I - \delta R)v = z + Ar$$

Eliminating  $v$  we get

$$w + Ar = A(I - \delta L)(A(I - \delta R))^{-1}(z + Ar)$$

$$w = Mz + q$$

$$w \geq 0 \perp z \geq 0$$

$$M = A(I - \delta L)(I - \delta R)^{-1}A, \quad q = (M - I)Ar$$

## Example

$$w = Mz + q$$

$$w \geq 0 \perp z \geq 0$$

$$M = A(I - \delta L)(I - \delta R)^{-1}A, \quad q = (M - I)Ar$$

$$A(I - \delta L) = \begin{pmatrix} 1 & 0 & -\delta & 0 \\ -\delta & 1 & 0 & 0 \\ 0 & 0 & -1 & \delta \\ 0 & 0 & \delta & -1 \end{pmatrix} \quad A(I - \delta R) = \begin{pmatrix} 1 & 0 & 0 & -\delta \\ 0 & 1 & 0 & -\delta \\ \delta & 0 & -1 & 0 \\ 0 & \delta & 0 & -1 \end{pmatrix}$$



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## Theorem [Levy-Desplanques]

If  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is strictly diagonally dominant, i.e.,  $|a_{ii}| > \sum_{j \neq i} |a_{ij}|$  for all  $i$ , then  $\mathbf{A}$  is non-singular.

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- $\mathbf{A}(\mathbf{I} - \delta \mathbf{L})$  and  $\mathbf{A}(\mathbf{I} - \delta \mathbf{R})$  are strictly diagonally dominant. E.g.

$$\mathbf{A}(\mathbf{I} - \delta \mathbf{L}) = \begin{pmatrix} 1 & 0 & -\delta & 0 \\ -\delta & 1 & 0 & 0 \\ 0 & 0 & -1 & \delta \\ 0 & 0 & \delta & -1 \end{pmatrix} \quad \mathbf{A}(\mathbf{I} - \delta \mathbf{R}) = \begin{pmatrix} 1 & 0 & 0 & -\delta \\ 0 & 1 & 0 & -\delta \\ \delta & 0 & -1 & 0 \\ 0 & \delta & 0 & -1 \end{pmatrix}$$

- So  $\mathbf{M} = \mathbf{A}(\mathbf{I} - \delta \mathbf{L})(\mathbf{I} - \delta \mathbf{R})^{-1} \mathbf{A}$  is well defined

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**Theorem [Johnson and Tsatsomeros (1995)]**

Let  $M = BC^{-1}$ , where  $B, C \in \mathbb{R}^{n \times n}$ . Then,  $M$  is a  $P$ -matrix if  $TC + (I - T)B$  is invertible for all  $T \in [0, I]$ .

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$$w = Mz + q$$

$$w \geq 0 \perp z \geq 0$$

$$M = A(I - \delta L)(I - \delta R)^{-1}A, \quad q = (M - I)Ar$$

$B = A(I - \delta L)$  and  $C = A(I - \delta R)$  are strictly diagonally dominant.

Thus,  $TC + (I - T)B$  is s.d.d., and hence invertible, for all  $T \in [0, I]$ .

Thus,  $M = BC^{-1}$  is a P-matrix.

## Discounted game PLCP: What is $q$ ?

Considering just the right successors  $\rho(\mathbf{s})$  we have

$$\mathbf{v}^\rho = \mathbf{r} + \delta \mathbf{v}^\rho(\rho(\mathbf{s}))$$

$$(I - \delta R) \mathbf{v}^\rho = \mathbf{r}$$

$$\mathbf{v}^\rho = (I - \delta R)^{-1} \mathbf{r}$$

and rewriting  $q$  in terms of  $\mathbf{v}^\rho$

$$\begin{aligned} q &= (M - I) A \mathbf{r} \\ &= A \delta (R - L) \mathbf{v}^\rho \end{aligned}$$

$$q_s = \begin{cases} +\delta[\mathbf{v}^\rho(\rho(\mathbf{s})) - \mathbf{v}^\rho(\lambda(\mathbf{s}))], & \mathbf{s} \in \mathbf{S}_{\text{Max}} \\ -\delta[\mathbf{v}^\rho(\rho(\mathbf{s})) - \mathbf{v}^\rho(\lambda(\mathbf{s}))], & \mathbf{s} \in \mathbf{S}_{\text{Min}} \end{cases}$$

# Strategy improvement algorithm

## Definition

State  $\mathbf{s} \in \mathbf{S}_{\text{Max}}$  is **switchable** under strategy pair defined by  $\rho$  if

$$v^\rho(\lambda(\mathbf{s})) > v^\rho(\rho(\mathbf{s}))$$

## Algorithm [Strategy Improvement for Max]

Start with  $\rho$  defined by arbitrary strategy **Max** and **Min**'s best response.

**loop:**

Obtain  $\rho'$  from  $\rho$  by changing at all switchable  $\mathbf{s} \in \mathbf{S}_{\text{Max}}$  under  $v^\rho$ .

Obtain  $\rho''$  from  $\rho'$  so **Min** plays best response.

if  $\rho'' \neq \rho'$  repeat with  $\rho \leftarrow \rho''$ .

# Why does strategy improvement work?

## Theorem [Global improvement from myopic improvement]

Let  $\rho$  and  $\rho'$  be the strategy pairs before and after some iteration.  
Then we have

$$\forall \mathbf{s} \in \mathbf{S} : v^{\rho'}(\mathbf{s}) \geq v^{\rho}(\mathbf{s}) ,$$

and

$$\exists \mathbf{s} \in \mathbf{S} : v^{\rho'}(\mathbf{s}) > v^{\rho}(\mathbf{s}) .$$

**Finite number** of pure positional **strategies** so algorithm terminates.

# Global improvement

- ▶ Want:  $\Delta = v^{\rho'}(\mathbf{s}) - v^{\rho}(\mathbf{s}) \geq 0$  for all  $\mathbf{s}$  and  $\Delta > 0$  for some  $\mathbf{s}$



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$$\Delta = \delta(R' v^{\rho'} - R v^{\rho})$$

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$$\begin{aligned}\Delta &= \delta(\mathbf{R}' \mathbf{v}^{\rho'} - \mathbf{R} \mathbf{v}^{\rho}) \\ &= \delta(\mathbf{R}' \mathbf{v}^{\rho'} - \mathbf{R}' \mathbf{v}^{\rho} + \mathbf{R}' \mathbf{v}^{\rho} - \mathbf{R} \mathbf{v}^{\rho})\end{aligned}$$

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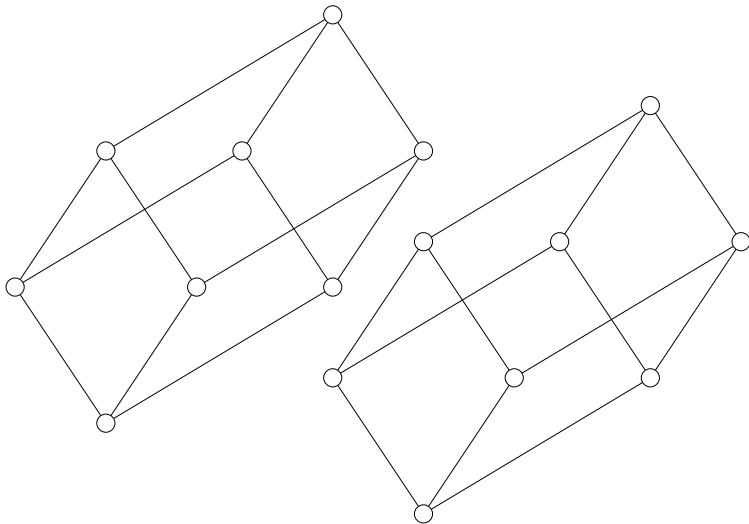
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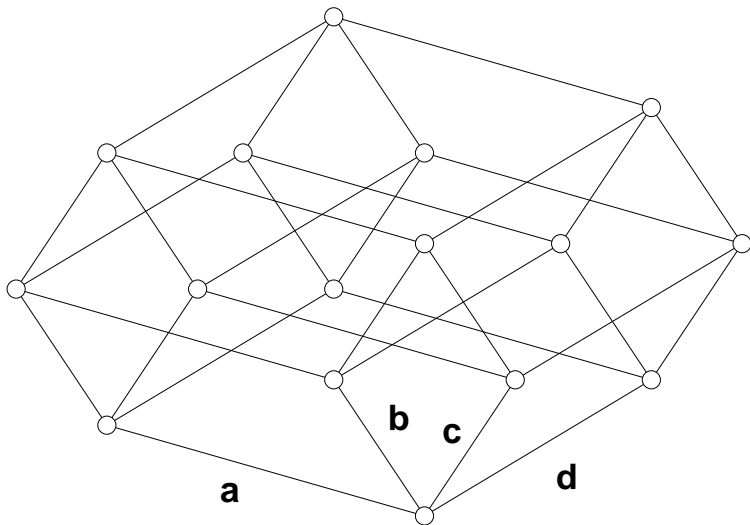
- ▶ If  $\mathbf{s} \in \mathbf{S}_{\text{Min}}$ , because  $\text{Min}$  was playing a best response:

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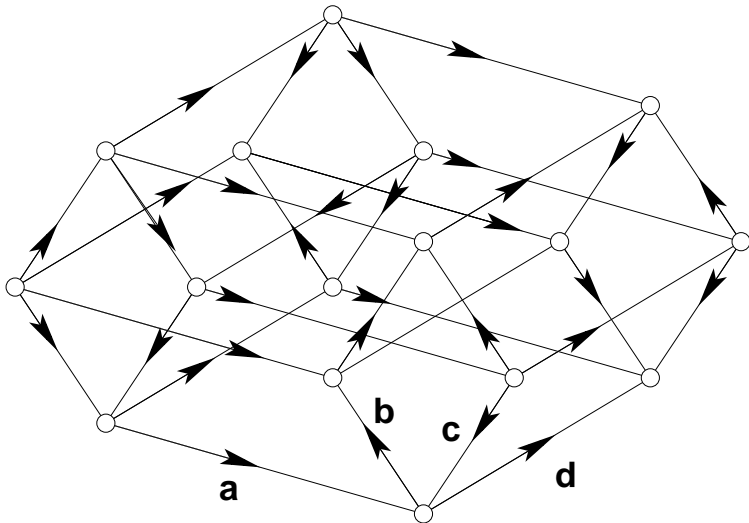
## Inherited USO



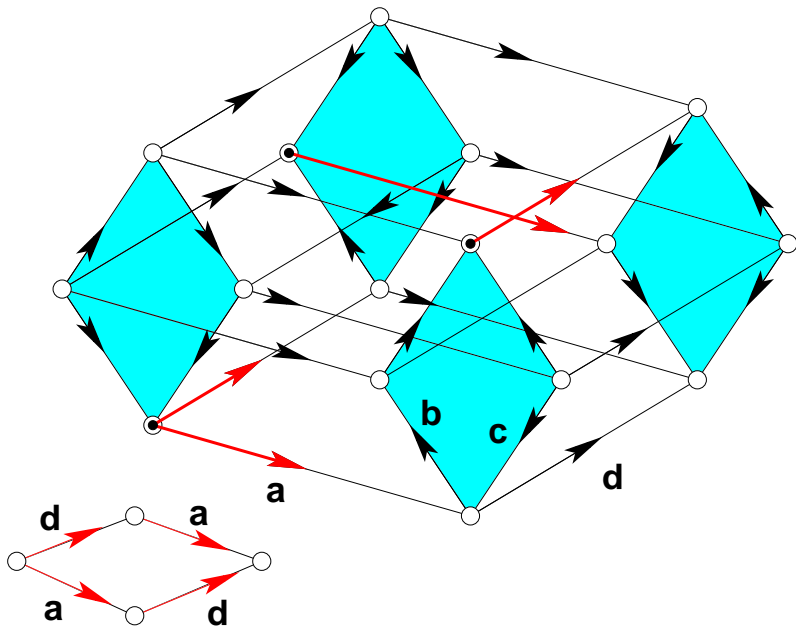
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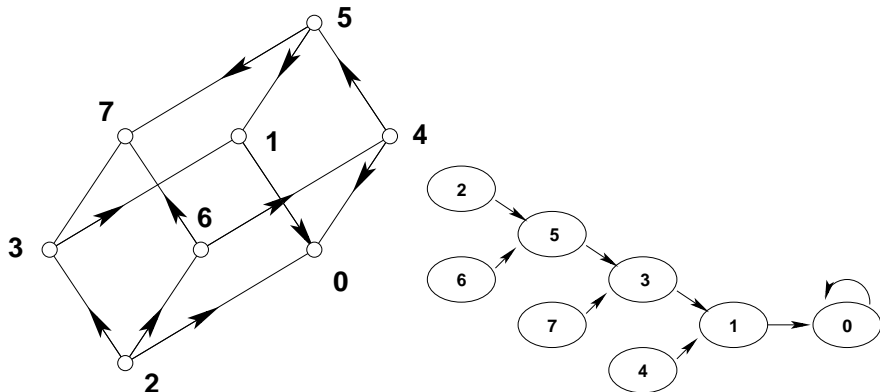


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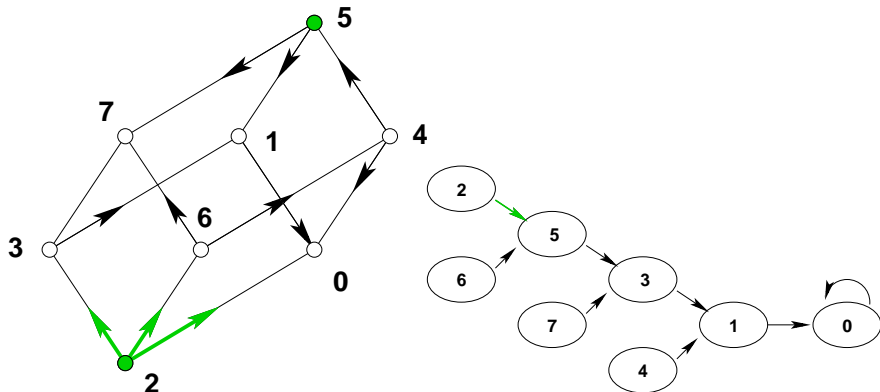




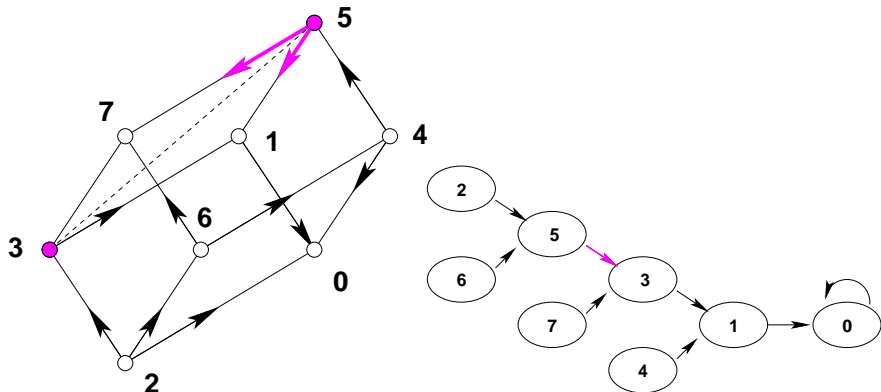
# Strategy Improvement = Bottom-Antipodal



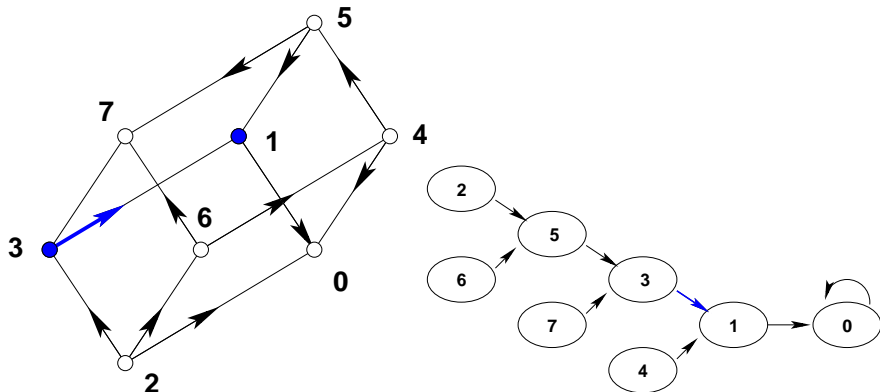
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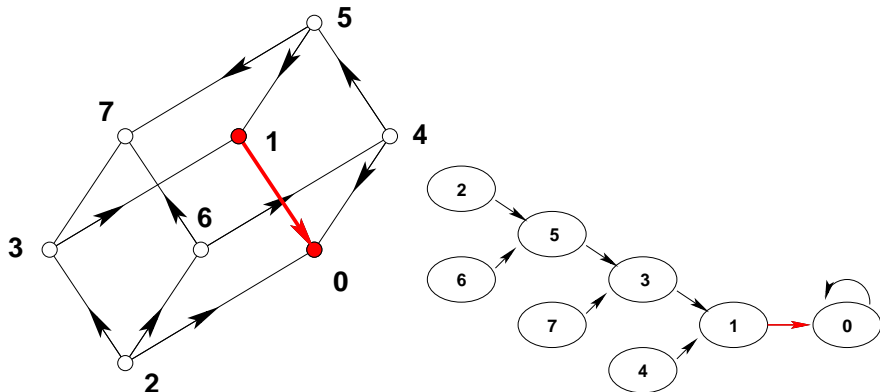
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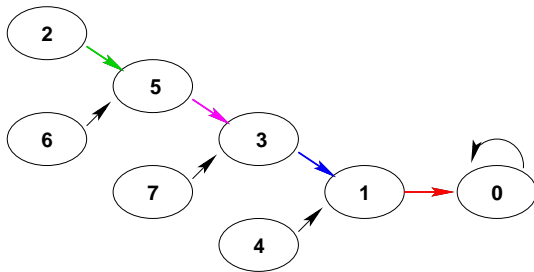
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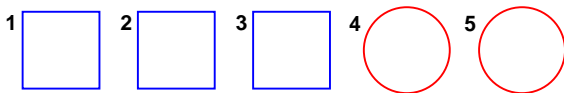
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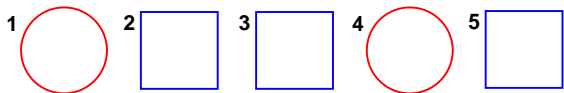
# Interpretation of Murty's least index method

## Algorithm

*Fix a permutation of states. Switch the switchable state with smallest index and repeat.*



**Max**'s states come first - variant of strategy improvement.



This is a new algorithm.

## Further research

- ▶ Polynomial-time algorithms!



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  - ▶ What strategy improvement (inherited) USOs arise from games?
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- ▶ Study **other LCP and USO algorithms applied to games**, e.g.,  
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