

Solution to Assignment 2

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1. *Solution:*

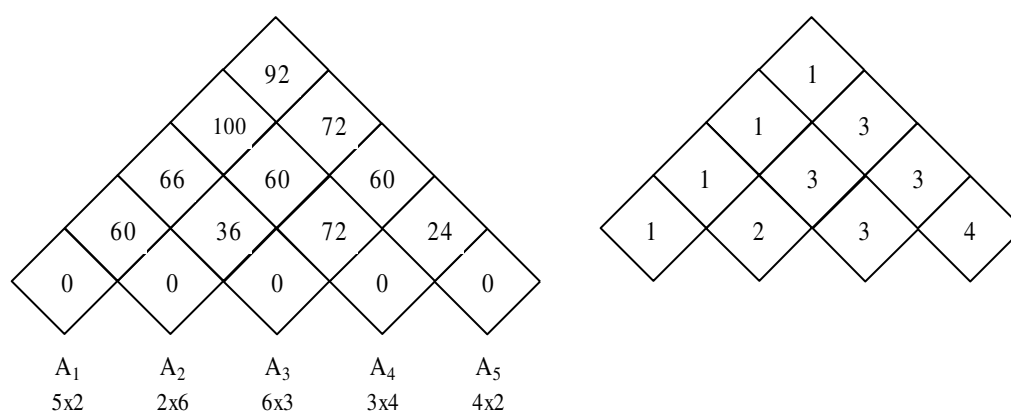


Figure 1: m and s tables

2. *Solution:*

- i. Use brute-force way to enumerate all possible subsets

```
function fs ( S )
    return fs_rec ( sum ( S ) / 2 , S )

function sum ( S )
    t = 0
    for every s in S
        t = t + w(s)
    return t

function fs_rec ( sum , S )
    if ( sum ( S ) < sum )
        return false
    elif ( sum ( S ) = sum )
        return S
    for every s in S
        res = fs_rec ( sum , S - {s} )
```

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```
    if ( res != false)
        return res
    return false
```

- ii. Use two dimensional table $R^{n \times w}$ (s is the maximal total weight)

```
function sum ( S )
    t = 0
    for every s in S
        t = t + w(s)
    return t

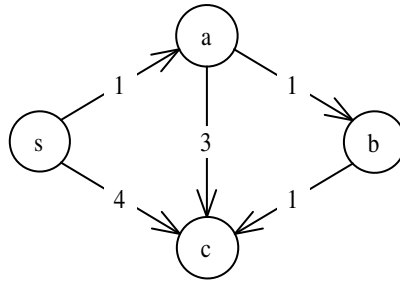
function fs ( S )
    w = sum ( S )
    if ( w is odd )
        return false
    else
        w = w / 2
    initialize table T[0..n, 0..w]
    initialize table G[0..n, 0..w]
    set T[0, k] to 0 , k = 0, 1, ..., w
    for i = 1 to n
        for j = 0 to w
            if ( j < S[i] )
                T[i, j] = T[i-1, j]
                G[i, j] = j
            else
                a = T[i-1, j]
                b = T[i-1, j-S[i]] + S[i]
                if a > b
                    T[i, j] = a
                    G[i, j] = j
                else
                    T[i, j] = b
                    G[i, j] = j-S[i]
    return get_result ( T , G , w )

function get_result ( T , G , w )
    result = {}
    for i = n downto 0
        if ( T [i, w] = w )
            add S[i] to result
            w = w - S[i]
    if ( result is empty )
        return false
    else
        return result
```

- iii. Discussion: solution (i) usually takes $O(n^n)$ time, which, though large, is still acceptable for this NP-hard problem; solution (ii) does not work if w is very large or fractional.

3. (a) Solution:

Figure 2 shows such an example:


 Figure 2: Example to show $T(i, v) \neq d_i(v)$

$T(i, v), i = 0$	$T(0, s) = 0$	$T(1, a) = \infty$	$T(0, b) = \infty$	$T(0, c) = \infty$
$T(i, v), i = 1$	$T(1, s) = 0$	$T(1, a) = 1$	$T(1, b) = \infty$	$T(1, c) = 4$
$d(v), \text{iteration } 0$	$d_0(s) = 0$	$d_0(a) = \infty$	$d_0(b) = \infty$	$d_0(c) = \infty$
$d(v), \text{iteration } 1$	$d_1(s) = 0$	$d_1(a) = 1$	$d_1(b) = 2$	$d_1(c) = 3$

The order of the edges considered is: $s \rightarrow a, a \rightarrow b, b \rightarrow c, a \rightarrow c, s \rightarrow c$.

So at the end of the first iteration, $T(1, v) \neq d_1(v)$, where $n = 5$.

3. (b) Proof:

- For $i = 0$, $T(i, s) = d(s) = 0$, $T(i, v) = d(v) = \infty, \forall v \neq s$.
- Suppose at the end of iteration i , $T(i, v) \geq d_i(v)$.

Then, at the end of iteration $i + 1$,

$$T(i + 1, v) = \min\{T(i, v), \min_{(u \neq v)} \{T(i, u) + w(u, v)\}\} \quad (1)$$

$$\geq \min\{d_i(v), \min_{(u \neq v)} \{d_i(u) + w(u, v)\}\} \quad (2)$$

$$\geq \min\{d_i(v), \min_{(u < v)} \{d_{i+1}(u) + w(u, v)\}, \min_{(u > v)} \{d_i(u) + w(u, v)\}\} \quad (3)$$

$$= d_{i+1}(v) \quad (4)$$

In (3), the inequation $u < v$ means the value of $d_i(u)$ is got before $d_i(v)$ in each iteration; and vice versa. I use the fact $d_i(v) \leq d_{i+1}(v)$.

■

3. (c) Solution:

The graph is shown in Figure 3.

In this case, $n = 4$. Suppose each iteration of both algorithms considers the edges in such an order: $b \rightarrow s, s \rightarrow c, s \rightarrow a, a \rightarrow b$.

$T(i, v), i = 0$	$T(0, s) = 0$	$T(1, a) = \infty$	$T(0, b) = \infty$	$T(0, c) = \infty$
$T(i, v), i = 1$	$T(1, s) = 0$	$T(1, a) = 1$	$T(1, b) = \infty$	$T(1, c) = 1$
$T(i, v), i = 2$	$T(2, s) = 0$	$T(2, a) = 1$	$T(2, b) = 2$	$T(2, c) = 1$
$T(i, v), i = 3$	$T(3, s) = -1$	$T(3, a) = 1$	$T(3, b) = 2$	$T(3, c) = 1$
$d(v), \text{iteration } 0$	$d_0(s) = 0$	$d_0(a) = \infty$	$d_0(b) = \infty$	$d_0(c) = \infty$
$d(v), \text{iteration } 1$	$d_1(s) = 0$	$d_1(a) = 1$	$d_1(b) = 2$	$d_1(c) = 1$
$d(v), \text{iteration } 2$	$d_2(s) = -1$	$d_2(a) = 0$	$d_2(b) = 1$	$d_2(c) = 0$
$d(v), \text{iteration } 3$	$d_3(s) = -2$	$d_3(a) = -1$	$d_3(b) = 0$	$d_3(c) = -1$

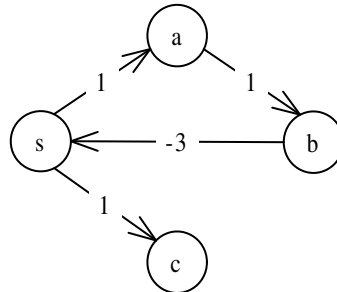


Figure 3: Example to show $T(n - 1, v) \neq d_{n-1}(v)$

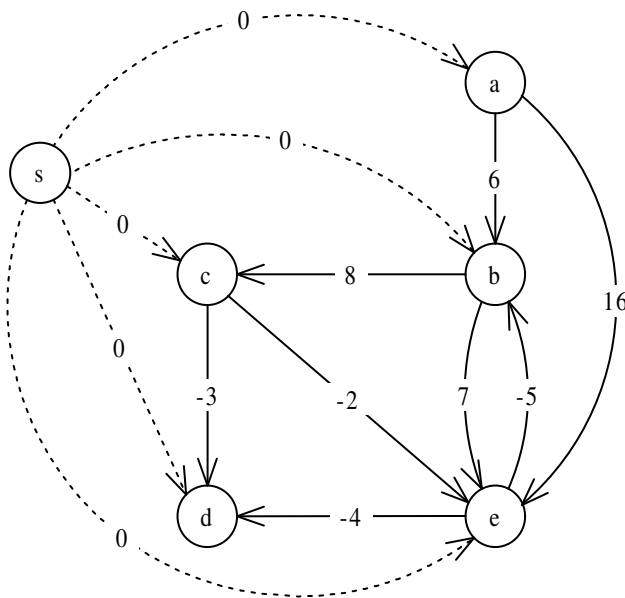


Figure 4: Example to show $T(n - 1, v) \neq d_{n-1}(v)$

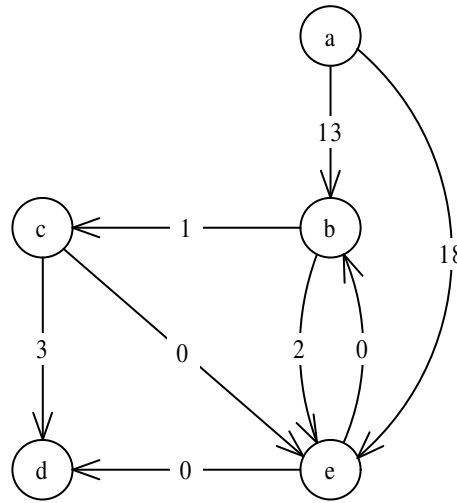


Figure 5: Reweighed graph

4. (a) Solution:

In Figure 4, vertex s is added. Below is the table of the execution of Bellman-Fort's algorithm. (Use $T(i, v)$ here.)

$T(i, v), i = 1$	$T(1, s) = 0$	$T(1, a) = 0$	$T(1, b) = 0$	$T(1, c) = 0$	$T(1, d) = 0$	$T(1, e) = 0$
$T(i, v), i = 2$	$T(2, s) = 0$	$T(2, a) = 0$	$T(2, b) = -5$	$T(2, c) = 0$	$T(2, d) = -4$	$T(2, e) = -2$
$T(i, v), i = 3$	$T(3, s) = 0$	$T(3, a) = 0$	$T(3, b) = -7$	$T(3, c) = 0$	$T(3, d) = -6$	$T(3, e) = -2$
$T(i, v), i = 4$	$T(4, s) = 0$	$T(4, a) = 0$	$T(4, b) = -7$	$T(4, c) = 0$	$T(4, d) = -6$	$T(4, e) = -2$
$T(i, v), i = 5$	$T(5, s) = 0$	$T(5, a) = 0$	$T(5, b) = -7$	$T(5, c) = 0$	$T(5, d) = -6$	$T(5, e) = -2$

4. (b) Solution:

From 4. (a) we know $h(a) = 0, h(b) = -7, h(c) = 0, h(d) = -6, h(e) = -2$. So we get the new weight function $\hat{w}(u, v)$:

$$\hat{w}(a, b) = 13, \hat{w}(a, e) = 18, \hat{w}(b, c) = 1, \hat{w}(b, e) = 2, \hat{w}(e, b) = 0, \hat{w}(e, d) = 0, \hat{w}(c, d) = 3, \hat{w}(c, e) = 0$$

4. (c) Solution:

Solution is given in Figure 6 (next page).

4. (d) Solution:

All-pairs shortest path for the graph is given below:

$\hat{\delta}(u, v)$	a	b	c	d	e	$\delta(u, v)$	a	b	c	d	e
a	0	13	14	14	14	a	0	6	14	8	12
b	∞	0	1	1	1	b	∞	0	8	2	6
c	∞	0	0	0	0	c	∞	-7	0	-6	-2
d	∞	∞	∞	0	∞	d	∞	∞	∞	0	∞
e	∞	0	1	0	0	e	∞	-5	3	-4	0

Note: Most of the students use Bellman-Ford algorithm on vertex a in the beginning, without giving any reason why. This is actually wrong! The reason is, not any vertex can do. Suppose instead of a , one takes b, c, d or e , after the reweighing, the edges $a \rightarrow b$ and $a \rightarrow e$ are deleted, simply because the Bellman-Ford algorithm returns ∞ for the shortest path to a .

For those who noticed this by the knowledge from the textbook, I give a bonus of 5 marks.

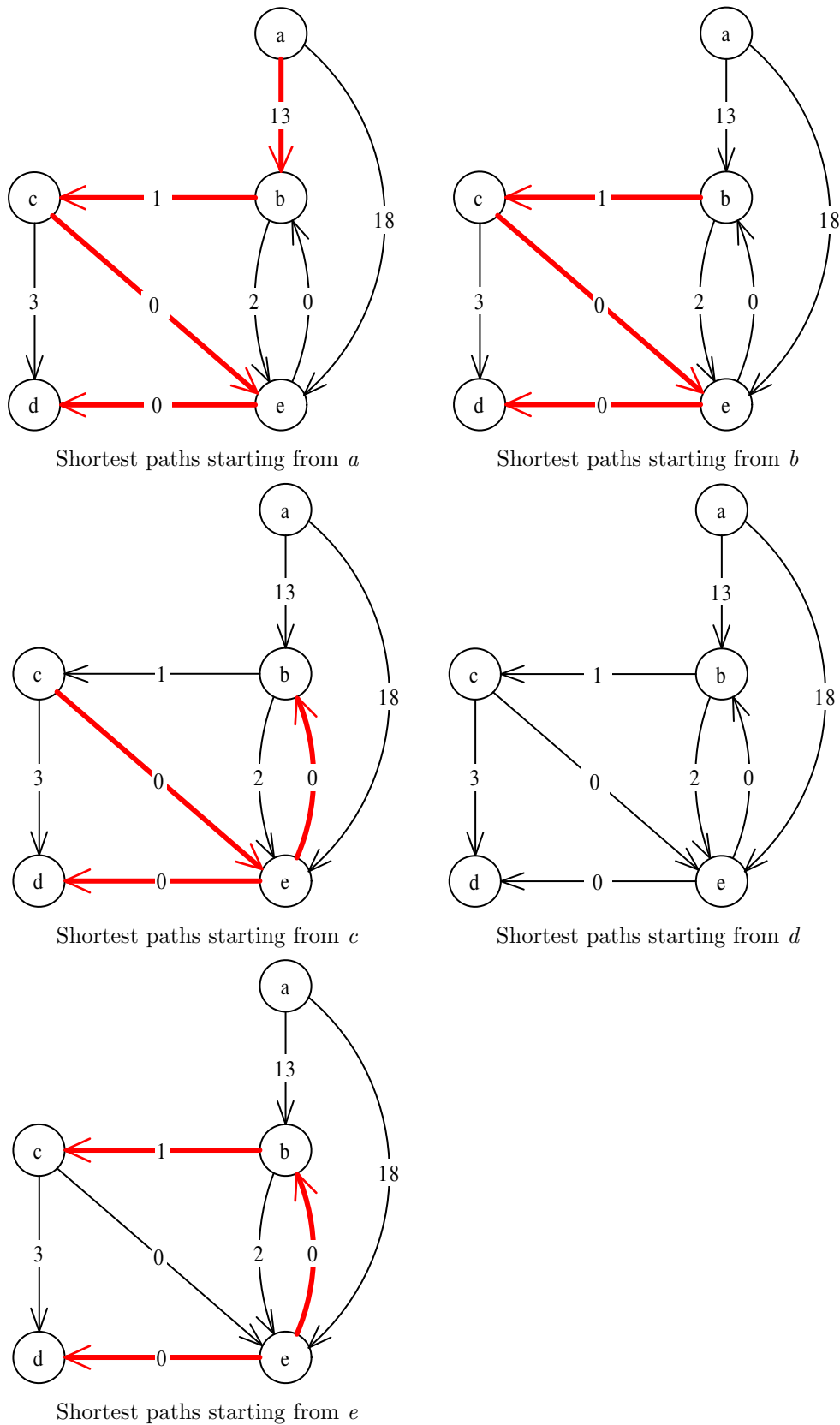


Figure 6: Dijkstra trees for all vertices